

# Dynamic Panel Data Models

## When the Past Predicts the Present

Jake Anderson

March 3, 2026

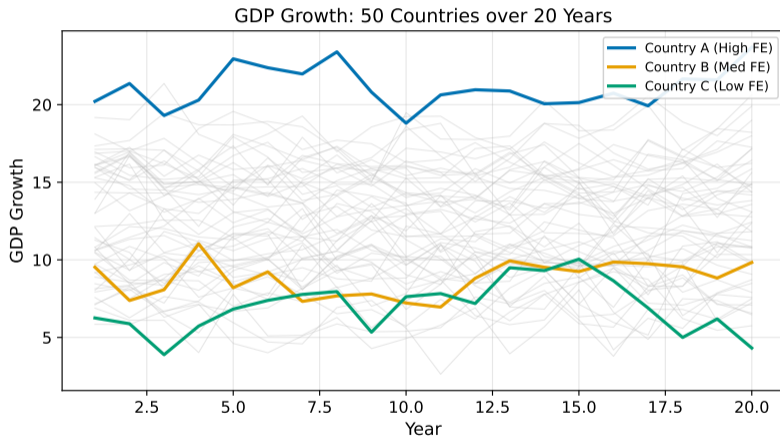
- 1 The Problem: Persistence in Panel Data
- 2 The FE Attempt and Nickell Bias
- 3 Arellano-Bond GMM
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# GDP Growth Across 50 Countries

Does this year's GDP growth depend on last year's? If so, how do we estimate that persistence?

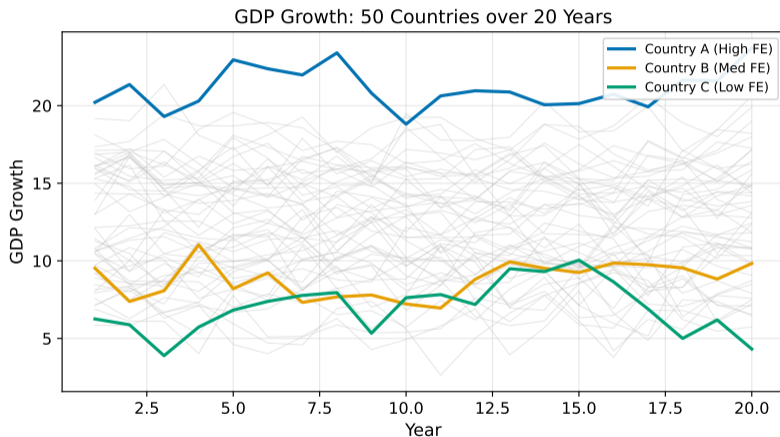
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Some countries consistently grow faster than others. And growth seems **sticky**: a good year tends to follow a good year.

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$\implies$  We need a model that includes **both** fixed effects and a lagged dependent variable.

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- $y_{i,t-1}$ : last year's growth (the **lagged dependent variable**)
- $\text{invest}_{it}$ : investment rate (exogenous regressor)
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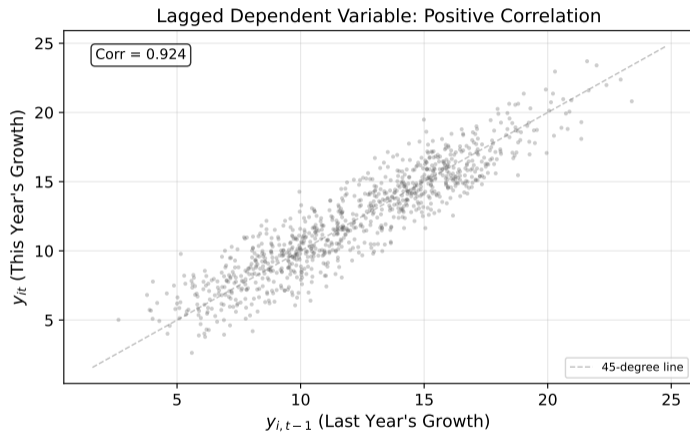
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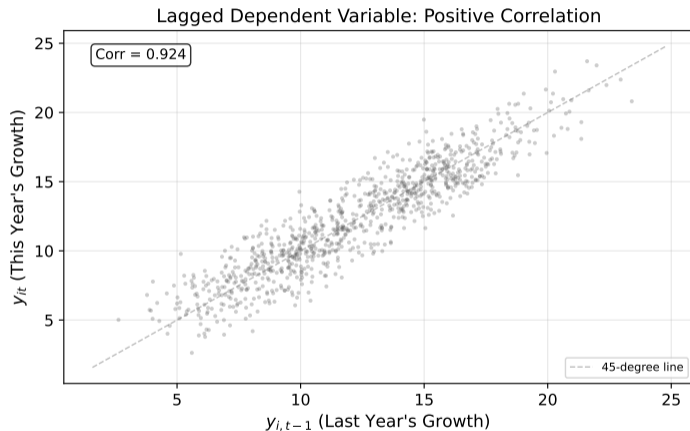
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Goal: estimate  $\rho$  consistently. True value in our simulation:  $\rho = 0.40$ .

# The Lagged Relationship

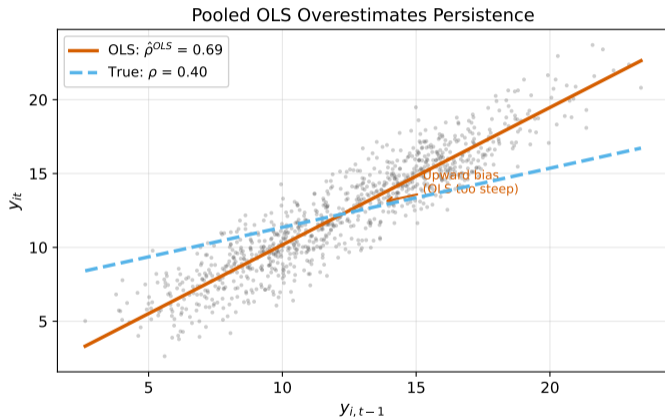


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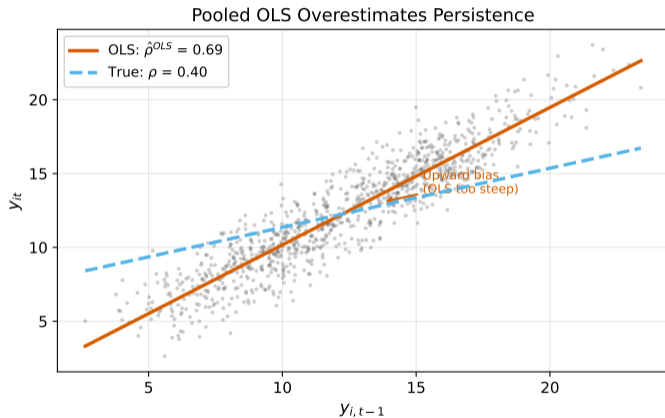


Strong positive correlation between  $y_{it}$  and  $y_{i,t-1}$ . But how much is true persistence, and how much is driven by the unobserved  $\alpha_i$ ?

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Formally,  $y_{i,t-1}$  depends on  $\alpha_i$  (since  $y_{i,t-1} = \rho y_{i,t-2} + \beta \text{invest}_{i,t-1} + \alpha_i + \varepsilon_{i,t-1}$ ), so:

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$\implies$  OLS **overestimates**  $\rho$  because it confuses level differences with persistence.

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## Fixed Effects: The Natural Fix?

FE removes  $\alpha_i$  by demeaning. The within-transformed model:

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Not quite. There is a subtle problem with demeaning when you have a lagged dependent variable.

## Nickell Bias: Demeaning Creates New Correlation

The demeaned lag  $\ddot{y}_{i,t-1} = y_{i,t-1} - \bar{y}_i$  is correlated with the demeaned error  $\ddot{\varepsilon}_{it} = \varepsilon_{it} - \bar{\varepsilon}_i$ .

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**Concrete example.** Suppose  $\varepsilon_{i,5}$  is a large positive shock.

- $\bar{y}_i$  includes  $y_{i,5}$ , which is inflated by  $\varepsilon_{i,5} \implies \bar{y}_i$  goes **up**.
- Look at year 4:  $\ddot{y}_{i,4} = y_{i,4} - \bar{y}_i$  goes **down** (the mean was inflated by the year-5 shock, but  $y_{i,4}$  was not).
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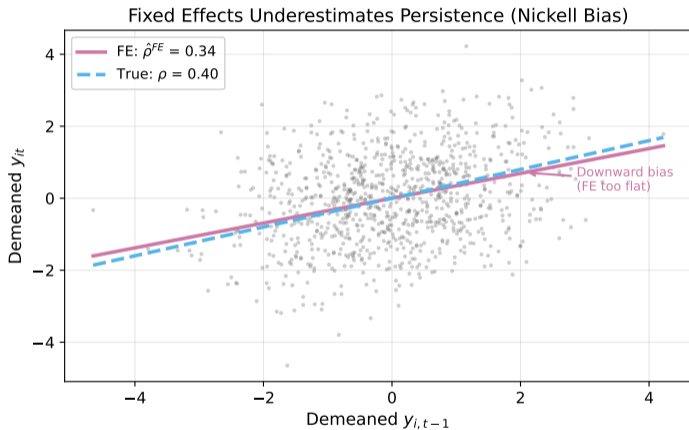
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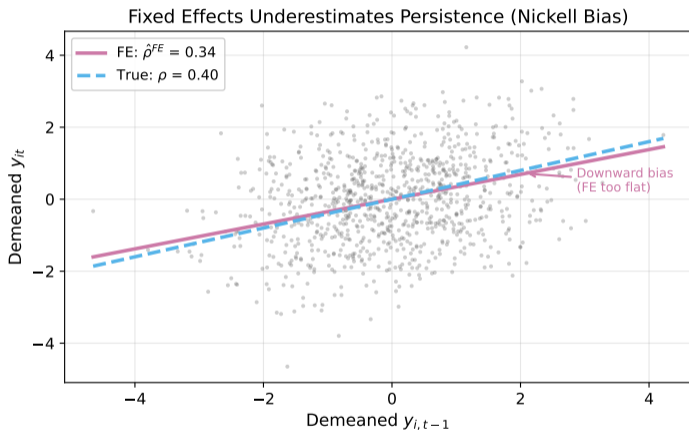
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This is the **Nickell bias** (Nickell, 1981). It arises purely from the mechanical relationship between demeaning and the lagged dependent variable.

# FE Estimate: Biased Downward

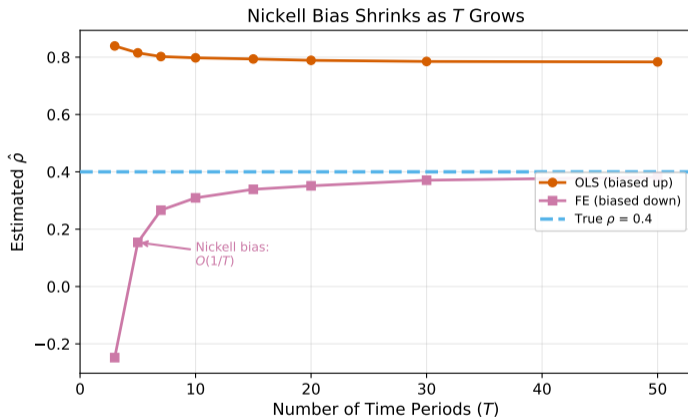


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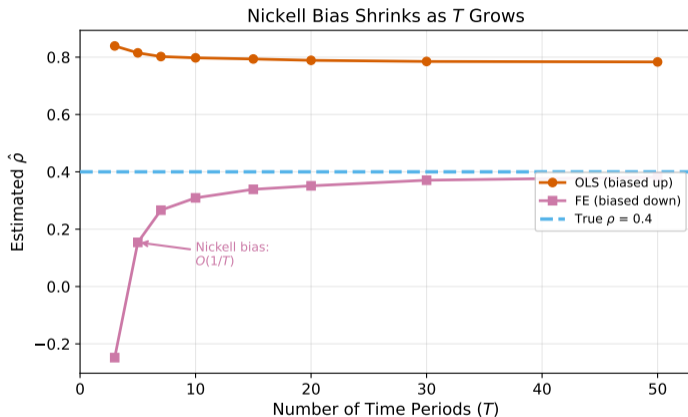


FE estimates  $\hat{\rho}^{FE} \approx 0.34$ , well below the true  $\rho = 0.40$ . FE overcorrects: it removes  $\alpha_i$  but introduces a new bias in the opposite direction.

# Nickell Bias Shrinks as $T$ Grows



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The FE bias is  $O(1/T)$  (roughly proportional to  $1/T$ ): it is severe for short panels ( $T = 3, 5$ ) but shrinks as  $T$  grows. The OLS bias barely moves because it stems from cross-sectional heterogeneity, not from  $T$ .

## The Bounds: OLS Up, FE Down

We now have two biased estimators that bracket the truth:

Estimator	$\hat{\rho}$	Bias direction
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Both OLS and FE are biased. Is there a way out?

# Two Problems, One Strategy

Where we stand:

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**The plan:**

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$\implies$  This is the Arellano-Bond (1991) approach.

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## Step 1: First-Difference to Eliminate $\alpha_i$

AB = Arellano-Bond. GMM = Generalized Method of Moments.

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What goes wrong if we try?

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OLS on the differenced data gives a slope of  $\approx -0.32$ , wildly wrong (true  $\rho = 0.40$ ). First-differencing removed  $\alpha_i$ , but something else went wrong. What?

## The Problem: $\Delta y_{i,t-1}$ and $\Delta \varepsilon_{it}$ Share a Term

Expand the terms:

$$\Delta y_{i,t-1} = y_{i,t-1} - y_{i,t-2} \quad \text{contains } \varepsilon_{i,t-1}$$

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What variable is correlated with  $\Delta y_{i,t-1}$  but uncorrelated with  $\Delta \varepsilon_{it}$ ?

## Step 2: Use $y_{i,t-2}$ as an Instrument

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### Relevance:

- $\Delta y_{i,t-1} = y_{i,t-1} - y_{i,t-2}$ , and  $y_{i,t-1}$  depends on  $y_{i,t-2}$  through the dynamic model
- $\implies \text{Corr}(y_{i,t-2}, \Delta y_{i,t-1}) \neq 0 \checkmark$

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### Validity (exclusion restriction):

- $\Delta \varepsilon_{it} = \varepsilon_{it} - \varepsilon_{i,t-1}$ , which contains only period- $t$  and period- $(t-1)$  errors
- $y_{i,t-2}$  depends on  $\varepsilon_{i,t-2}$  and earlier, not on  $\varepsilon_{i,t-1}$  or  $\varepsilon_{it}$
- $\implies \text{Cov}(y_{i,t-2}, \Delta \varepsilon_{it}) = 0 \checkmark$  (assuming no serial correlation in  $\varepsilon$ )

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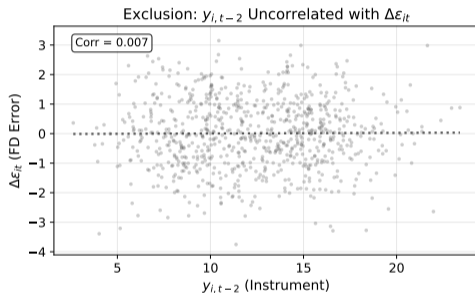
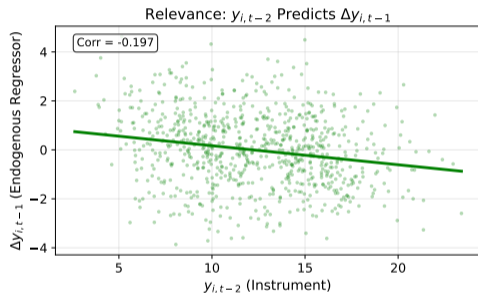
### Validity (exclusion restriction):

- $\Delta \varepsilon_{it} = \varepsilon_{it} - \varepsilon_{i,t-1}$ , which contains only period- $t$  and period- $(t-1)$  errors
- $y_{i,t-2}$  depends on  $\varepsilon_{i,t-2}$  and earlier, not on  $\varepsilon_{i,t-1}$  or  $\varepsilon_{it}$
- $\implies \text{Cov}(y_{i,t-2}, \Delta \varepsilon_{it}) = 0 \checkmark$  (assuming no serial correlation in  $\varepsilon$ )

This exclusion restriction is an **assumption**. It fails if the original errors  $\varepsilon_{it}$  are serially correlated, since then  $y_{i,t-2}$  would correlate with  $\varepsilon_{i,t-1}$  inside  $\Delta \varepsilon_{it}$ .

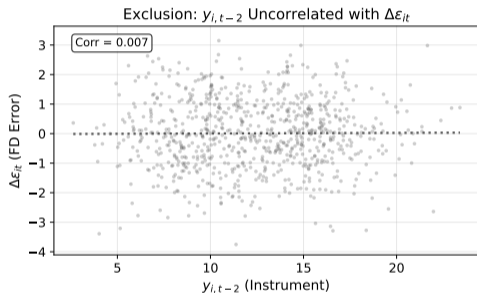
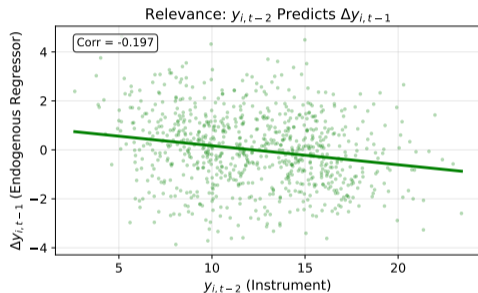
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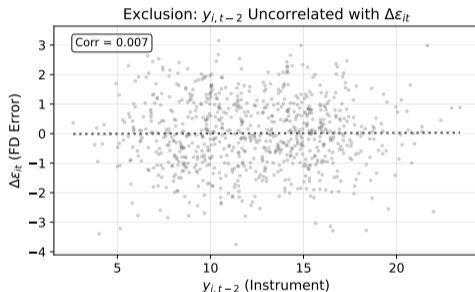
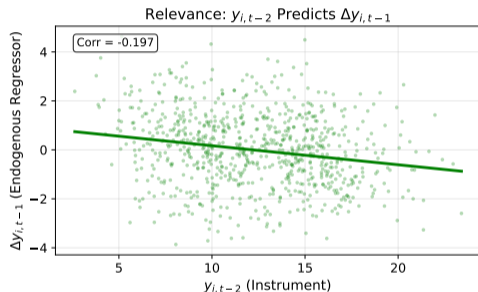
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Left:  $y_{i,t-2}$  predicts  $\Delta y_{i,t-1}$  (relevance). The correlation is negative because  $y_{i,t-2}$  appears with a minus sign in  $\Delta y_{i,t-1} = y_{i,t-1} - y_{i,t-2}$ . Any nonzero correlation suffices for relevance.

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Right:  $y_{i,t-2}$  is uncorrelated with  $\Delta \varepsilon_{it}$  (exclusion). This single-period instrument looks weak, but AB uses many lags, which collectively provide strong identification.

# Expanding the Instrument Set

The set of valid instruments **grows with**  $t$ :

Period	Available instruments for $\Delta y_{i,t-1}$
$t = 3$	$y_{i,1}$
$t = 4$	$y_{i,1}, y_{i,2}$
$t = 5$	$y_{i,1}, y_{i,2}, y_{i,3}$
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This creates many **moment conditions**. A moment condition is a restriction on population averages. Here, it says each instrument is uncorrelated with the error, the same logic as an IV exclusion restriction:

$$E[y_{i,s} \cdot \Delta \varepsilon_{it}] = 0 \quad \text{for all } s \leq t - 2$$

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We need a way to combine all these moment conditions into a single estimate. That is what GMM does.

# GMM: Combining Many Instruments

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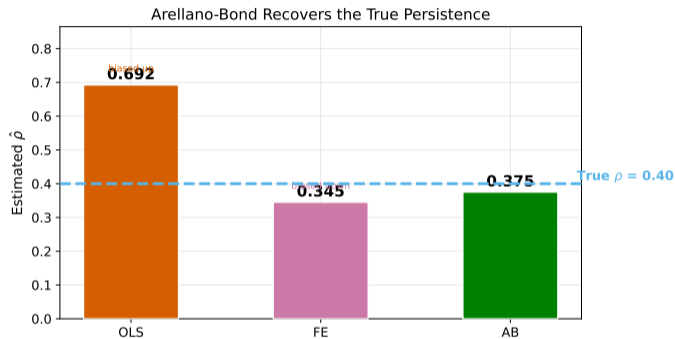
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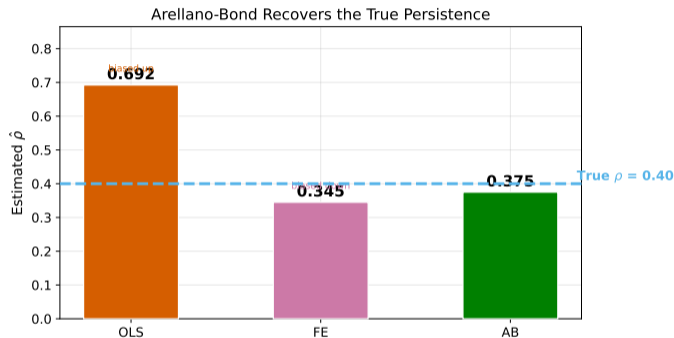
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*Note:* “One-step” GMM uses a preliminary weighting matrix; “two-step” re-estimates with an optimal weighting matrix from step-1 residuals. Two-step is more efficient.

# The Result: AB Recovers the True $\rho$

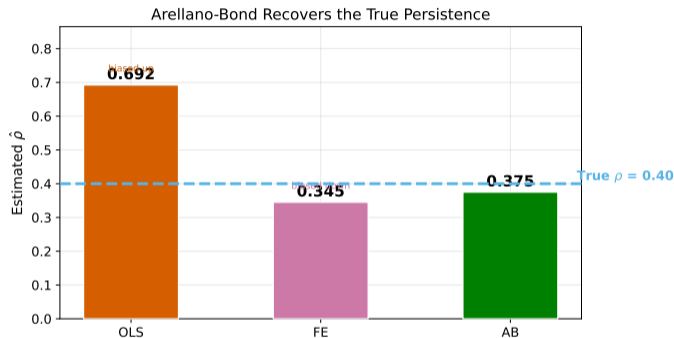


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$\implies$  By first-differencing (to remove  $\alpha_i$ ) and instrumenting (to handle the  $\Delta\varepsilon_{it}$  correlation), AB produces a consistent estimator.

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- AR(2) in  $\Delta\varepsilon$ : we should *not* find this. Why?  $\Delta\varepsilon_{it}$  and  $\Delta\varepsilon_{i,t-2}$  share no terms unless  $\varepsilon_{it}$  itself is autocorrelated. So AR(2) in the differenced errors is really a test for AR(1) in the original errors.

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- We have more instruments than strictly needed. The Sargan test checks whether they all agree. If some instruments give very different answers, at least one is probably invalid.
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$\implies$  Report both tests. If AR(2) is significant or Sargan rejects, the AB assumptions are in doubt.

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⇒ Always report AR(2) and Sargan/Hansen  $p$ -values alongside your AB estimates.

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$\implies$  We need additional instruments. Where do they come from?

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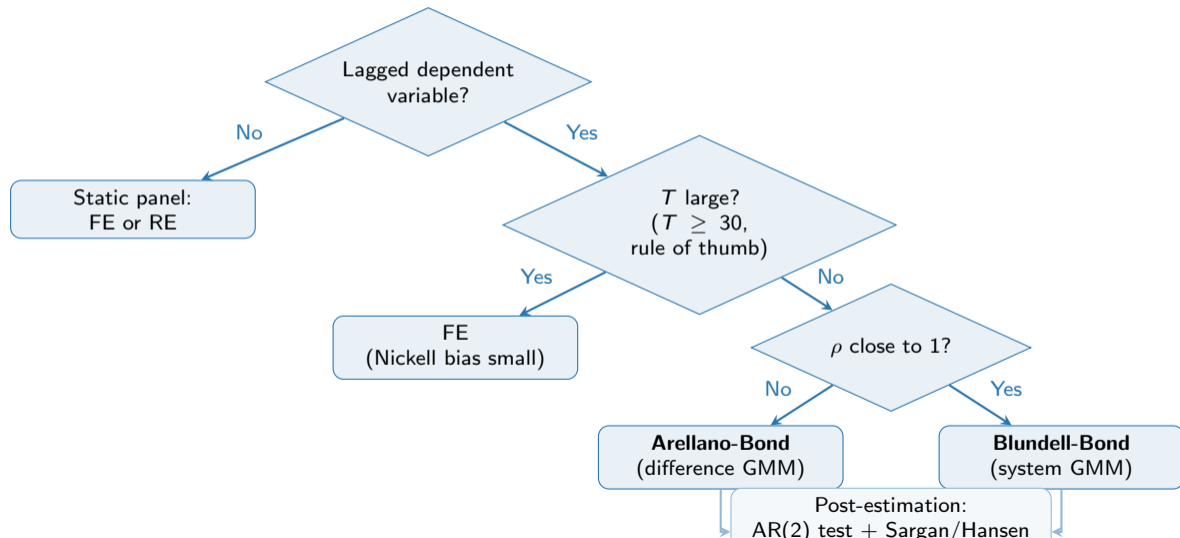
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⇒ System GMM adds an assumption:  $E[\Delta y_{i,t} \cdot \alpha_j] = 0$  (each country's growth has settled to its long-run average by the start of the sample). This is testable via the difference-in-Sargan test.

# Outline

- 1 The Problem: Persistence in Panel Data
- 2 The FE Attempt and Nickell Bias
- 3 Arellano-Bond GMM
- 4 Decision Framework**
- 5 Summary

# Decision Flowchart



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$\implies$  When your panel model has a lagged dependent variable and small  $T$ , use AB or System GMM, not OLS or FE. First-difference to remove the fixed effect, then instrument to restore consistency.

**Thank you!**

jakeanderson@g.ucla.edu